



Multiaxial fatigue

an introduction

Multiaxial fatigue

- uniaxial fatigue

- One stress (strain) component

- Fatigue related to amplitude and mid value of this component

- Multiaxial fatigue

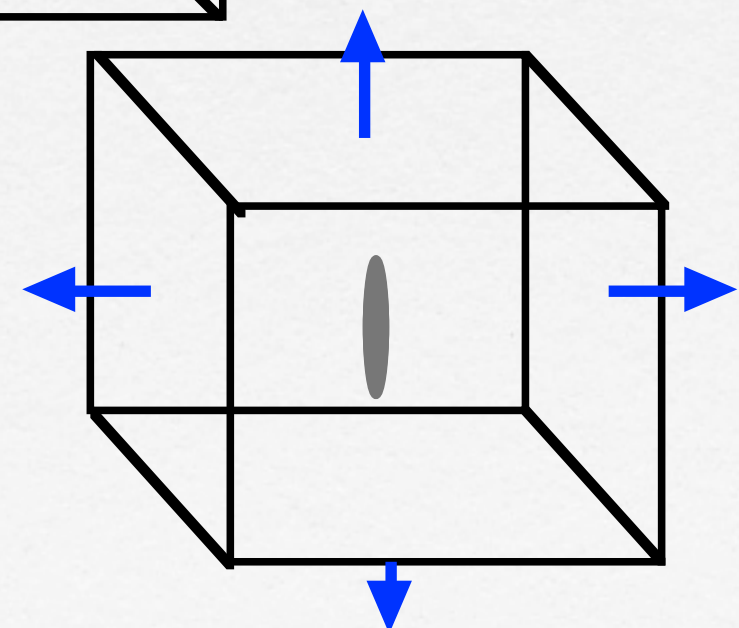
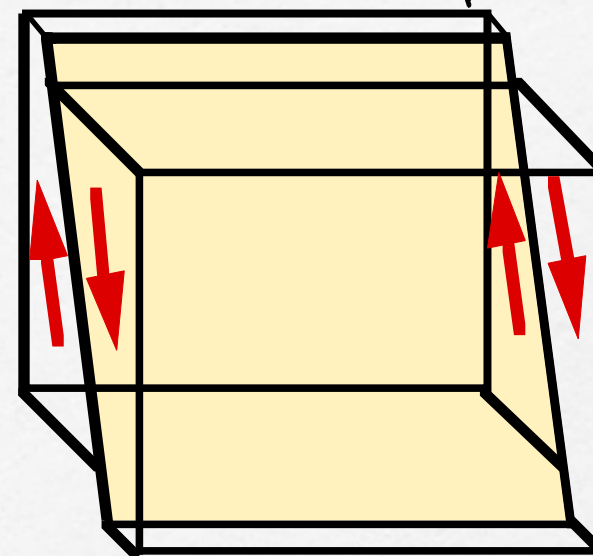
- Six independent components

- What is the amplitude and mid value?

- Assume that, in the general case, fatigue behaviour is influenced by

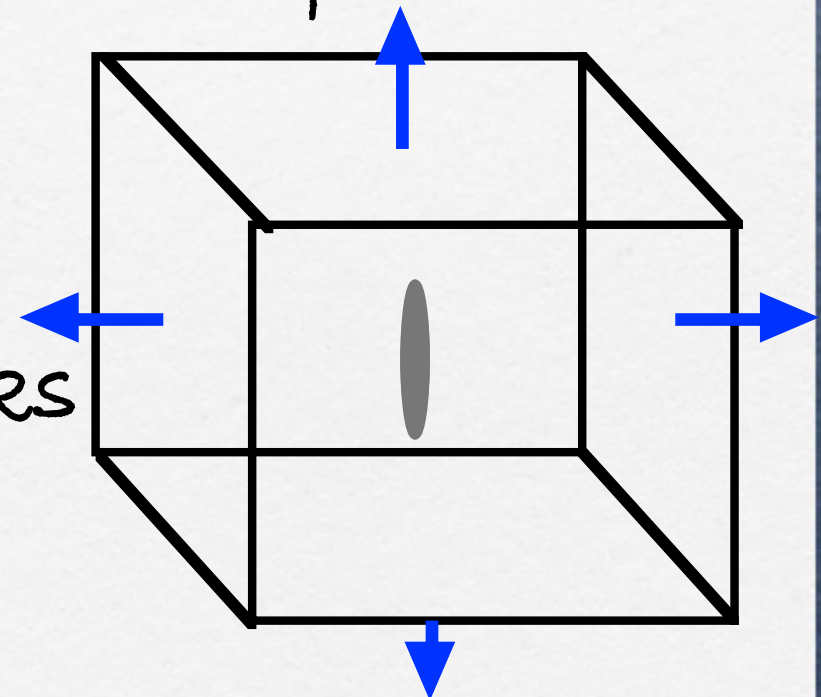
- shear stress

- hydrostatic stress



Hydrostatic stress

- The hydrostatic stress is the mean value of normal stresses acting on the material point (positive in tension)
- A tensile (positive) hydrostatic stress opens up microscopic cracks



$$\sigma_h = (\sigma_x + \sigma_y + \sigma_z)/3$$

- The hydrostatic stress is a stress invariant

$$\sigma_h = \sigma_{ii}/3$$

- regardless of coordinate system

Shear stress measures

- The shear stress initiates slip bands which leads to microscopic cracks
- Since a static shear stress have no influence on the fatigue damage, the shear stress "amplitude" is employed

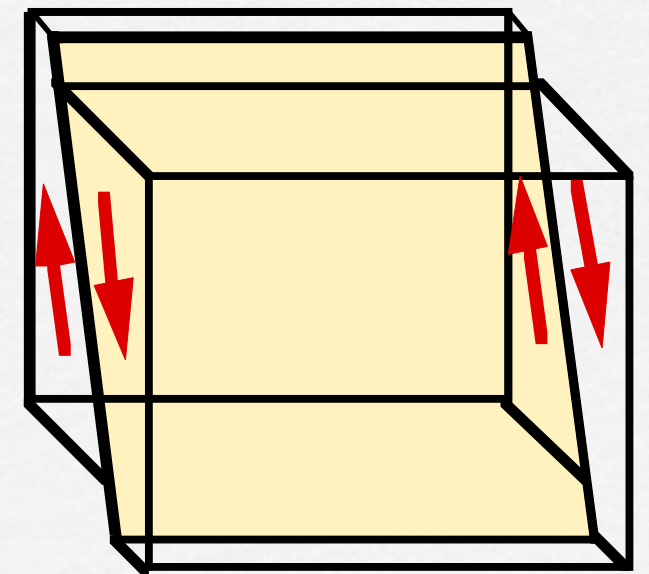
- Two usual measures

- Tresca shear stress

$$\tau_{Tr} = (\sigma_1 - \sigma_3)/2$$

- von Mises stress

$$\sigma_{vM} = \sqrt{(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2} / \sqrt{2}$$



Shear stress “amplitude”

- Empirical experience: *superposed static shear stress* does not have any influence on the fatigue limit:

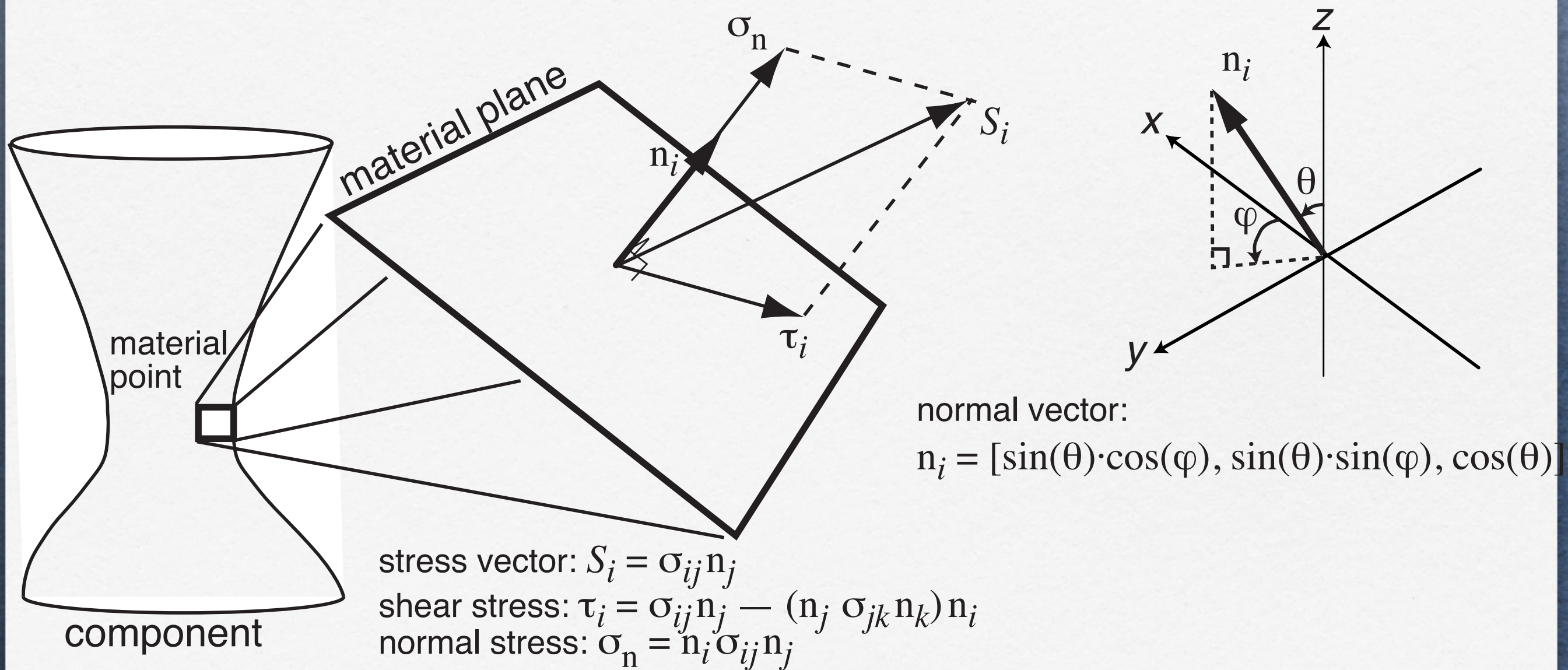
$$\tau_{FL} = \tau_{FLP}$$

whereas

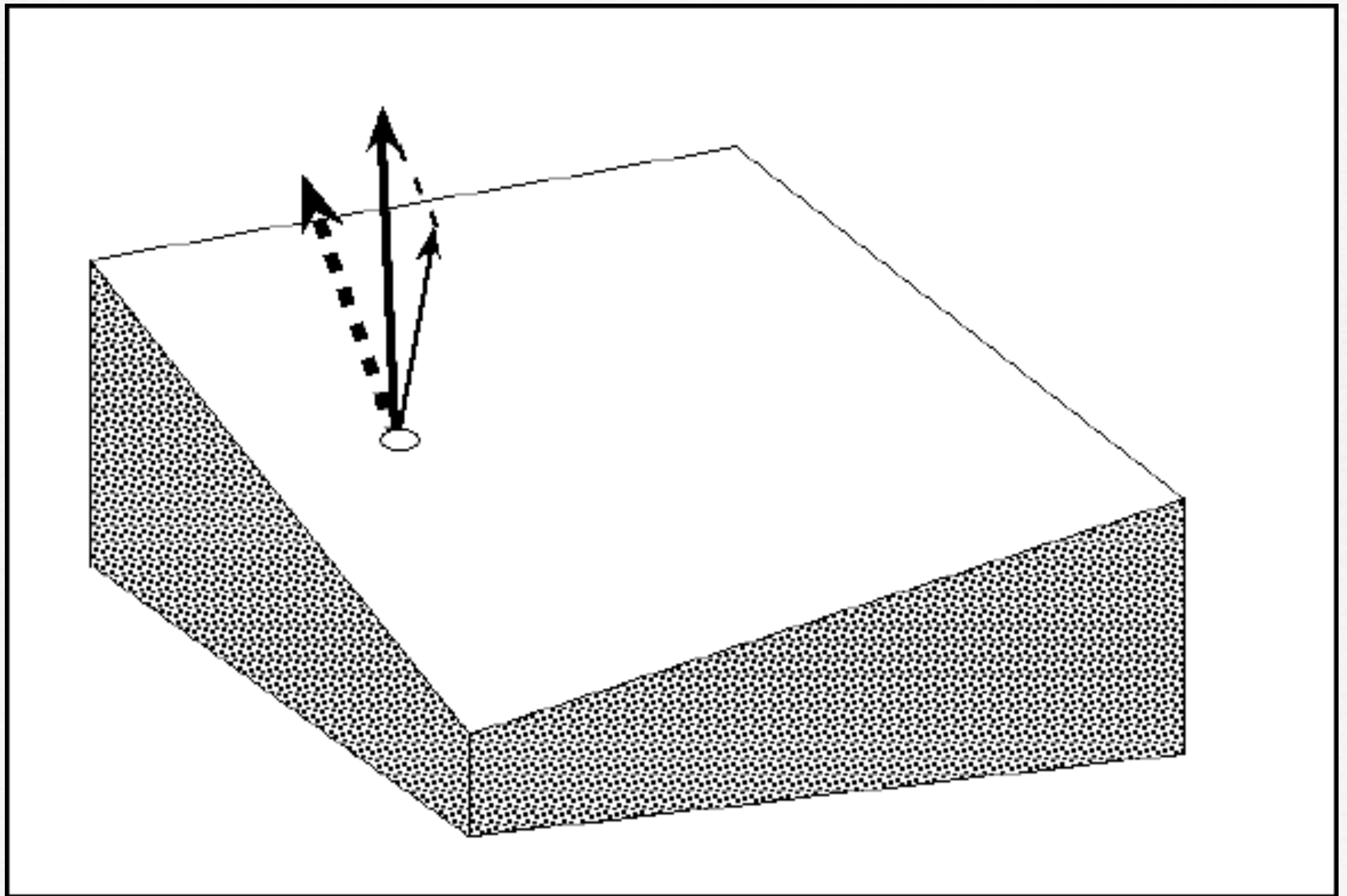
$$\sigma_{FL} \neq \sigma_{FLP}$$

- A shear stress “*amplitude*” is therefore needed in multiaxial fatigue initiation (HCF) criteria
- This “amplitude” the difference between *current shear stress* magnitude and the *mid value of the shear stress* for the current stress cycle

Stresses in a material point



Shear stress path



The deviatoric stress tensor

- The stress tensor

$$\sigma_{ij} = \begin{bmatrix} \sigma_{xx} & \tau_{xy} & \tau_{xz} \\ \tau_{yz} & \sigma_{yy} & \tau_{yz} \\ \tau_{zx} & \tau_{zy} & \sigma_{zz} \end{bmatrix}$$

- split in a volumetric and a deviatoric part

$$\sigma_{ij} = \begin{bmatrix} \sigma_{xx} & \tau_{xy} & \tau_{xz} \\ \tau_{yz} & \sigma_{yy} & \tau_{yz} \\ \tau_{zx} & \tau_{zy} & \sigma_{zz} \end{bmatrix} = \sigma_h \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} + \begin{bmatrix} \sigma_{xx} - \sigma_h & \tau_{xy} & \tau_{xz} \\ \tau_{yz} & \sigma_{yy} - \sigma_h & \tau_{yz} \\ \tau_{zx} & \tau_{zy} & \sigma_{zz} - \sigma_h \end{bmatrix}$$
$$= \sigma_h \mathbf{I} + \mathbf{S}^d$$

- the volumetric part contains the **hydrostatic stress**
- the deviatoric part reflects the **shear stress**

“Amplitude” of deviatoric stress

$$\sigma_{ij,a}^d(t) = \sigma_{ij}^d(t) - \sigma_{ij,m}^d$$

with $\sigma_{ij,m}^d$ from *time dependent*

$$\min[\max_{(t \in T)} [J_2(\sigma_{ij,m}^d(t) - \sigma_{ij,m}^d)]]$$

where

$$J_2 \equiv \sigma_{vM} = \sqrt{\frac{3}{2} \sigma_{ij}^d \sigma_{ij}^d}$$

Shear stress “amplitude”

- We can express the “amplitude” of the Tresca and von Mises stress using this “amplitude” of the deviatoric stress tensor

$$\tau_{\text{Tr},a}(t) = \frac{\sigma_{a,1}^d(t) - \sigma_{a,3}^d(t)}{2}$$

with

$$\sigma_{a,1}^d(t) = (\sigma_{ij}^d(t) - \sigma_{m,ij}^d)_1$$

and

$$\sigma_{\text{vM}}(t) = \sqrt{\frac{3}{2} \sigma_{a,ij}^d(t) \sigma_{a,ij}^d(t)}$$

with

$$\sigma_{a,ij}^d(t) = \sigma_{ij}^d(t) - \sigma_{m,ij}^d$$

Criteria for equivalent stress

□ Dang Van

$$\sigma_{\text{EQDV}}(t) = \frac{\sigma_{a,1}^d(t) - \sigma_{a,3}^d(t)}{2} + a_{dv}\sigma_h(t)$$

with

$$\sigma_h(t) = \frac{\sigma_x(t) + \sigma_y(t) + \sigma_z(t)}{3}$$

□ Crossland

$$\sigma_{\text{EQC}}(t) = \sqrt{\frac{3}{2}\sigma_{a,ij}^d(t)\sigma_{a,ij}^d(t)} + c_C\sigma_{h,\max}$$

with

$$\sigma_{h,\max} = \max_t(\sigma_h(t))$$

Proportional multiaxial loading

□ Proportional loading

$$\sigma_{ij} = a_{ij} + c_{ij} \cdot f(t)$$

a_{ij} and c_{ij} are constants

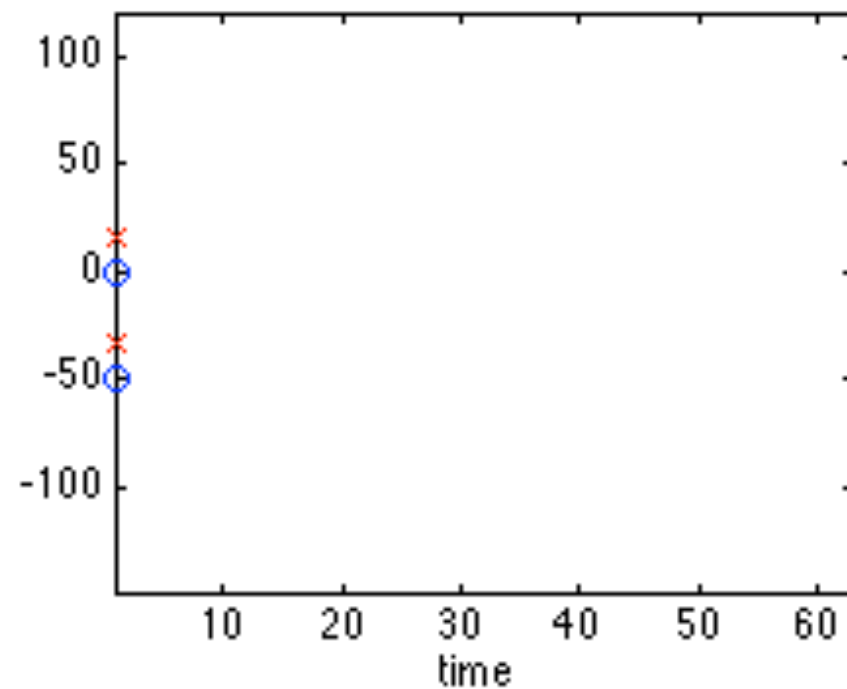
$f(t)$ is a common time function

□ Fixed principal directions:

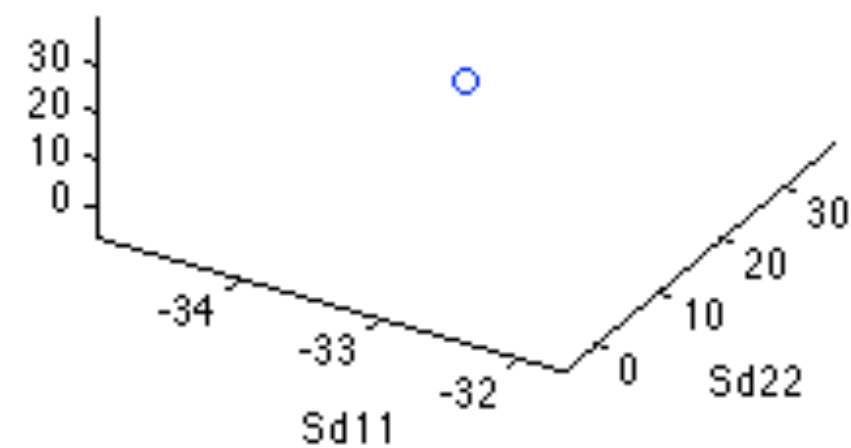
the components correspond to a fix direction

$$\begin{aligned} \sigma_{ij}^d(t) &= \begin{bmatrix} \sigma_{xx}^d(t) & \tau_{xy}^d(t) & \tau_{xz}^d(t) \\ \tau_{yx}^d(t) & \sigma_{yy}^d(t) & \tau_{yz}^d(t) \\ \tau_{zx}^d(t) & \tau_{zy}^d(t) & \sigma_{zz}^d(t) \end{bmatrix} = \begin{bmatrix} \sigma_1^d(t) & 0 & 0 \\ 0 & \sigma_2^d(t) & 0 \\ 0 & 0 & \sigma_3^d(t) \end{bmatrix} \\ &= \begin{bmatrix} a_{11}^d & 0 & 0 \\ 0 & a_{22}^d & 0 \\ 0 & 0 & a_{33}^d \end{bmatrix} + \begin{bmatrix} c_{11}^d & 0 & 0 \\ 0 & c_{22}^d & 0 \\ 0 & 0 & c_{33}^d \end{bmatrix} \cdot f(t) \end{aligned}$$

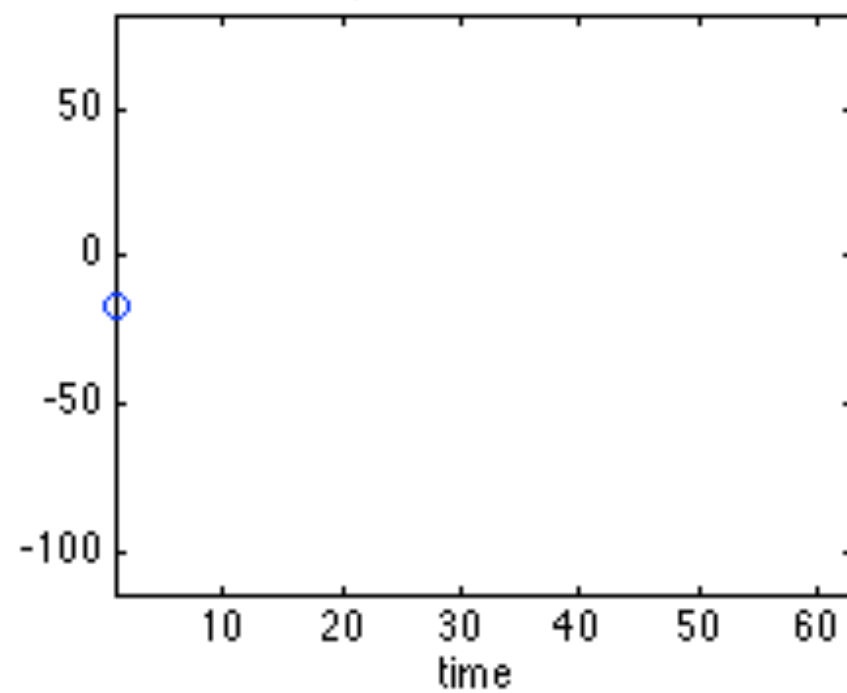
Stress components



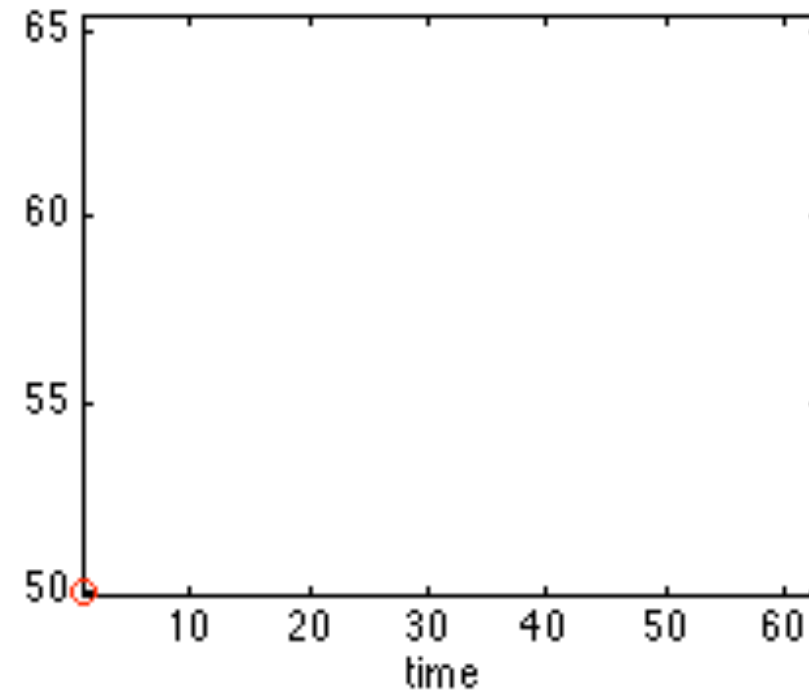
Principal components of the deviatoric stress tensor - $t=1$



Hydrostatic stress



von Mises effective stress



Shear stress “amplitude”

- For in-phase loading with fixed principal directions (proportional loading), we can express the “amplitude” of the Tresca and von Mises stress using the “amplitude” of the deviatoric stress tensor

$$\tau_{\text{Tresca},a}(t) = \frac{\sigma_{1,a}^d(t) - \sigma_{3,a}^d(t)}{2} \qquad \sigma_{1,a}^d(t) = \sigma_1^d(t) - \sigma_{1,m}^d$$

$$\sigma_{\text{vM},a} = \frac{1}{\sqrt{2}} \sqrt{(\sigma_{1,a}^d - \sigma_{2,a}^d)^2 + (\sigma_{2,a}^d - \sigma_{3,a}^d)^2 + (\sigma_{3,a}^d - \sigma_{1,a}^d)^2}$$

it can be shown that σ_a and σ_a^d yields the same results

$$\tau_{\text{Tresca},a} = \frac{\sigma_{1,a} - \sigma_{3,a}}{2} \qquad \sigma_{1,a} = \frac{\sigma_{1,\text{max}} - \sigma_{1,\text{min}}}{2}$$

$$\sigma_{\text{vM},a} = \frac{1}{\sqrt{2}} \cdot \sqrt{(\sigma_{1,a} - \sigma_{2,a})^2 + (\sigma_{2,a} - \sigma_{3,a})^2 + (\sigma_{3,a} - \sigma_{1,a})^2}$$

Equivalent stress criteria

□ *Sines*

$$\sigma_{EQS} = \frac{1}{\sqrt{2}} \sqrt{(\sigma_{1,a}^d - \sigma_{2,a}^d)^2 + (\sigma_{2,a}^d - \sigma_{3,a}^d)^2 + (\sigma_{3,a}^d - \sigma_{1,a}^d)^2} + c_S \sigma_{h,mid} > \sigma_{eS}$$

□ *Crossland*

$$\sigma_{EQC} = \frac{1}{\sqrt{2}} \sqrt{(\sigma_{1,a} - \sigma_{2,a})^2 + (\sigma_{2,a} - \sigma_{3,a})^2 + (\sigma_{3,a} - \sigma_{1,a})^2} + c_C \sigma_{h,max} > \sigma_{eC}$$

□ *Dang Van*

$$\sigma_{EQDV} = \frac{\sigma_{1,a} - \sigma_{3,a}}{2} + c_{DV} \sigma_{h,max} > \sigma_{eDV}$$